## AP CALCULUS AB and BC

## Final $\mathcal{N}$ otes

## Differentiation Formulas

1. $\frac{d}{d x}\left(x^{n}\right)=n x^{n-1}$
2. $\frac{d}{d x}(f g)=f g^{\prime}+g f^{\prime}$ Product rule
3. $\frac{d}{d x}\left(\frac{f}{g}\right)=\frac{g f^{\prime}-f g^{\prime}}{g^{2}}$ Quotient rule
4. $\frac{d}{d x} f(g(x))=f^{\prime}(g(x)) g^{\prime}(x)$ Chain rule
5. $\frac{d}{d x}(\sin x)=\cos x$
6. $\frac{d}{d x}(\cos x)=-\sin x$
7. $\frac{d}{d x}(\tan x)=\sec ^{2} x$
8. $\frac{d}{d x}(\cot x)=-\csc ^{2} x$
9. $\frac{d}{d x}(\sec x)=\sec x \tan x$
10. $\frac{d}{d x}(\csc x)=-\csc x \cot x$
11. $\frac{d}{d x}\left(e^{x}\right)=e^{x}$
12. $\frac{d}{d x}\left(a^{x}\right)=a^{x} \ln a$
13. $\frac{d}{d x}(\ln x)=\frac{1}{x}$
14. $\frac{d}{d x}(\operatorname{Arcsin} x)=\frac{1}{\sqrt{1-x^{2}}}$
15. $\frac{d}{d x}(\operatorname{Arctan} x)=\frac{1}{1+x^{2}}$
16. $\frac{d}{d x}(\operatorname{Arcsec} x)=\frac{1}{|x| \sqrt{x^{2}-1}}$
17. $\frac{d}{d x}[c]=0$
18. $\frac{d}{d x}[c f(x)]=c f^{\prime}(x)$

## Integration Formulas

1. $\int a d x=a x+C$
2. $\int x^{n} d x=\frac{x^{n+1}}{n+1}+C, \quad n \neq-1$
3. $\int \frac{1}{x} d x=\ln |x|+C \int \frac{d u}{u}=\ln |u|+C \quad \int \frac{f^{\prime}(x)}{f(x)} d x=\ln |f(x)|+C \quad \int \frac{k}{x} d x=k \ln |x|+C$
4. $\int e^{x} d x=e^{x}+C \quad \int f^{\prime}(x) e^{f(x)} d x=e^{f(x)}+C \quad \int e^{k x} d x=\frac{1}{k} e^{k x}+C \quad\{$ Shortcut $\}$
5. $\int a^{x} d x=\frac{a^{x}}{\ln a}+C \quad \int a^{u} d u=\frac{a^{u}}{\ln a}+C \quad \int f^{\prime}(x) a^{f(x)} d x=\frac{a^{f(x)}}{\ln a}+C$
6. $\int \ln x d x=x \ln x-x+C$
7. $\int \sin x d x=-\cos x+C$
8. $\int \cos x d x=\sin x+C$
9. $\int \tan x d x=\ln |\sec x|+C$ or $-\ln |\cos x|+C$
10. $\int \cot x d x=\ln |\sin x|+C$
11. $\int \sec x d x=\ln |\sec x+\tan x|+C$
12. $\int \csc x d x=-\ln |\csc x+\cot x|+C$
13. $\int \sec ^{2} x d x=\tan x+C$
14. $\int \sec x \tan x d x=\sec x+C$
15. $\int \csc ^{2} x d x=-\cot x+C$
16. $\int \csc x \cot x d x=-\csc x+C$
17. $\int \tan ^{2} x d x=\tan x-x+C$
18. $\int \frac{d x}{a^{2}+x^{2}}=\frac{1}{a} \operatorname{Arctan}\left(\frac{x}{a}\right)+C$
19. $\int \frac{d x}{\sqrt{a^{2}-x^{2}}}=\operatorname{Arcsin}\left(\frac{x}{a}\right)+C$
20. $\int \frac{d x}{x \sqrt{x^{2}-a^{2}}}=\frac{1}{a} \operatorname{Arcsec} \frac{|x|}{a}+C=\frac{1}{a} \operatorname{Arccos}\left|\frac{a}{x}\right|+C$

| Shortcuts |
| :--- |
| $\int \sin (k x) d x=-\frac{1}{k} \cos (k x)+C$ |
| $\int \cos (k x) d x=\frac{1}{k} \sin (k x)+C$ |
| $\int \sec ^{2}(k x) d x=\frac{1}{k} \tan (k x)+C$ |
| $\int \sec (k x) \tan (k x) d x=\frac{1}{k} \sec (k x)+C$ |
| $\int \csc ^{2}(k x) d x=-\frac{1}{k} \cot (k x)+C$ |
| $\int \csc (k x) \cot (k x) d x=-\frac{1}{k} \csc (k x)+C$ |
| $\int \tan (k x) d x=-\frac{1}{k} \ln \|\cos (k x)\|+C=\frac{1}{k} \ln \|\sec (k x)\|+C$ |
| $\int \sec (k x) d x=\frac{1}{k} \ln \|\sec (k x)+\tan (k x)\|+C$ |
| $\int \csc (k x) d x=-\frac{1}{k} \ln \|\csc (k x)+\cot (k x)\|+C$ |
| $\int \cot (k x) d x=\frac{1}{k} \ln \|\sin (k x)\|+C$ |

## Formulas, Concepts, and Theorems

## 1. Limits and Continuity:

A function $y=f(x)$ is continuous at $x=a$ if
i). $\quad f(a)$ exists
ii). $\quad \lim _{x \rightarrow a} f(x)$ exists
iii). $\quad \lim _{x \rightarrow a} f(x)=f(a)$

Otherwise, $f$ is discontinuous at $x=a$.
The limit $\lim _{\mathrm{x} \rightarrow \mathrm{a}} f(\mathrm{x})$ exists if and only if both corresponding one-sided limits exist and are equal that is,

$$
\lim _{\mathrm{x} \rightarrow \mathrm{a}} f(\mathrm{x})=\mathrm{L} \rightarrow \lim _{\mathrm{x} \rightarrow \mathrm{a}^{+}} f(\mathrm{x})=\mathrm{L}=\lim _{\mathrm{x} \rightarrow \mathrm{a}^{-}} f(\mathrm{x})
$$

## 2. Even and Odd Functions

1. A function $y=f(x)$ is even if $f(-x)=f(x)$ for every $x$ in the function's domain. Every even function is symmetric about the $y$-axis.
2. A function $y=f(x)$ is odd if $f(-x)=-f(x)$ for every $x$ in the function's domain.

Every odd function is symmetric about the origin.
3. Periodicity

A function $f(x)$ is periodic with period $p(p>0)$ if $f(x+p)=f(x)$ for every value of $x$
Note: The period of the function $y=A \sin (B x+C)$ or $y=A \cos (B x+C)$ is $\frac{2 \pi}{|B|}$.
The amplitude is $|A|$. The period of $y=\tan x$ is $\pi$.

## 4. Intermediate-Value Theorem

A function $y=f(x)$ that is continuous on a closed interval $[a, b]$ takes on every value between $f(a)$ and $f(b)$.
Note: If $f$ is continuous on $[a, b]$ and $f(a)$ and $f(b)$ differ in sign, then the equation $f(x)=0$ has at least one solution in the open interval $(a, b)$.
5. Limits of Rational Functions as $x \rightarrow \pm \infty$
i). $\quad \lim _{x \rightarrow \pm \infty} \frac{f(x)}{g(x)}=0$ if the degree of $f(x)<$ the degree of $g(x)$

Example: $\lim _{x \rightarrow \infty} \frac{x^{2}-2 x}{x^{3}+3}=0$
ii). $\quad \lim _{x \rightarrow \pm \infty} \frac{f(x)}{g(x)}$ is infinite if the degrees of $f(x)>$ the degree of $g(x)$

Example: $\lim _{x \rightarrow \infty} \frac{x^{3}+2 x}{x^{2}-8}=\infty$
iii). $\quad \lim _{x \rightarrow \pm \infty} \frac{f(x)}{g(x)}$ is finite if the degree of $f(x)=$ the degree of $g(x)$

$$
\text { Example: } \lim _{x \rightarrow \infty} \frac{2 x^{2}-3 x+2}{10 x-5 x^{2}}=-\frac{2}{5}
$$

6. Horizontal and Vertical Asymptotes
7. A line $y=b$ is horizontal asymptote of the graph $y=f(x)$ if either $\lim _{x \rightarrow \infty} f(x)=b$ or $\lim _{x \rightarrow-\infty} f(x)=b$.(Compare degrees of functions in fraction)
8. A line $x=a$ is a vertical asymptote of the graph $y=f(x)$ if either $\lim _{x \rightarrow a^{+}} f(x)= \pm \infty$ or $\lim _{x \rightarrow a^{-}} f(x)= \pm \infty$ (Values that make the denominator 0 but not numerator)
9. Average and Instantaneous Rate of Change
i). Average Rate of Change: If $\left(x_{0}, y_{0}\right)$ and $\left(x_{1}, y_{1}\right)$ are points on the graph of $y=f(x)$, then the average rate of change of $y$ with respect to $x$ over the interval $\left[x_{0}, x_{1}\right]$ is $\frac{f\left(x_{1}\right)-f\left(x_{0}\right)}{x_{1}-x_{0}}=\frac{y_{1}-y_{0}}{x_{1}-x_{0}}=\frac{\Delta y}{\Delta x} .\{$ old fashioned way of finding slope $\}$
ii). Instantaneous Rate of Change: If $\left(x_{0}, y_{0}\right)$ is a point on the graph of $y=f(x)$, then the instantaneous rate of change of $y$ with respect to $x$ at $x_{0}$ is $f^{\prime}\left(x_{0}\right)$. \{new fashioned way of finding slope $\}$
10. Definition of Derivative

$$
f^{\prime}(x)=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h} \text { or } f^{\prime}(a)=\lim _{x \rightarrow a} \frac{f(x)-f(a)}{x-a}
$$

The latter definition of the derivative is the instantaneous rate of change of $f(\mathrm{x})$ with respect to $x \quad$ at $x=a$. $\{$ i.e. the slope at $x=a\}$
Geometrically, the derivative of a function at a point is the slope of the tangent line to the graph of the function at that point.
9. The Number $e$ as a limit $* * *$ BC only
i). $\quad \lim _{n \rightarrow \infty}\left(1+\frac{1}{n}\right)^{n}=e$
ii). $\quad \lim _{n \rightarrow 0}(1+n)^{1 / n}=e$
10. Rolle's Theorem (this is a weak version of the MVT)

If $f$ is continuous on $[a, b]$ and differentiable on $(a, b)$ such that $f(a)=f(b)$, then there is at least one number $c$ in the open interval $(a, b)$ such that $f^{\prime}(c)=0$.
11. Mean Value Theorem

If $f$ is continuous on $[a, b]$ and differentiable on $(a, b)$, then there is at least one number $c$ in $(a, b)$ such that $\frac{f(b)-f(a)}{b-a}=f^{\prime}(c)$.
12. Extreme-Value Theorem

If $f$ is continuous on a closed interval $[a, b]$, then $f(x)$ has both a maximum and minimum on $[a, b]$.
13. $\quad$ Absolute Mins and Maxs: To find the maximum and minimum values of a function $y=f(x)$ on a CLOSED interval, locate

1. the points where $f^{\prime}(x)$ is zero or where $f^{\prime}(x)$ fails to exist. \{Must be within the given interval\}
2. the end points, if any, on the domain of $f(x)$.
3. Plug those values into $f(x)$ to see which gives you the max and which gives you this min values (the $x$-value is where that value occurs)
Note: These are the only candidates for the value of $x$ where $f(x)$ may have a maximum or a minimum.
4. Increasing and Decreasing:
5. If $f^{\prime}(x)>0$ for every $x$ in $(a, b)$, then $f$ is increasing on $[a, b]$.
6. If $f^{\prime}(x)<0$ for every $x$ in $(a, b)$, then $f$ is decreasing on $[a, b]$.

## Relative mins and maxs:

1. Relative Max - if $f^{\prime}$ switches from positive to negative at $x=a$, then $(a, f(a))$ is a relative max of $f$.
2. Relative Min - if $f^{\prime}$ switches from negative to positive at $x=a$, then $(a, f(a))$ is a relative min of $f$.
3. Concavity:
4. If $f^{\prime \prime}(x)>0$ in $(a, b),\left\{f^{\prime}\right.$ is increasing $\}$ then $f$ is concave upward in $(a, b)$.
5. If $f^{\prime \prime}(x)<0$ in $(a, b),\left\{f^{\prime}\right.$ is decreasing $\}$ then $f$ is concave downward in $(a, b)$.

To locate the points of inflection of $y=f(x)$, find the points where $f^{\prime \prime}(x)=0$ or where $f^{\prime \prime}(x)$ fails to exist $\left\{\right.$ or the $x$-values where $f^{\prime}$ has mins and maxs $\}$. These are the only candidates where $f(x)$ may have a point of inflection. Then test these points to make sure that $f^{\prime \prime}(x)<0$ on one side and $f^{\prime \prime}(x)>0$ on the other.

16a. Differentiability and Continuity Theorem: If a function is differentiable at point $x=a$, it is continuous at that point. The converse is false, in other words, continuity does not imply differentiability.

16b. Local Linearity and Linear Approximations \{aka "Tangent lines"\}
The linear approximation to $f(x)$ near $x=x_{0}$ is given by $y=f\left(x_{0}\right)+f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right)$ for $x$ sufficiently close to $x_{0}$. In other words, find the equation of the tangent line at $\left(x_{0}, f\left(x_{0}\right)\right)$ and use that equation to approximate the value at the value you need an estimate for.
17. $* * *$ Dominance and Comparison of Rates of Change (BC topic only)

Logarithm functions grow slower than any power function $\left(x^{n}\right)$.
Among power functions, those with higher powers grow faster than those with lower powers. All power functions grow slower than any exponential function ( $\mathrm{a}^{\mathrm{x}}, \mathrm{a}>1$ ).
Among exponential functions, those with larger bases grow faster than those with smaller bases. We say, that as $\mathrm{x} \rightarrow \infty$ :

1. $f(x)$ grows faster than $g(x)$ if $\lim _{x \rightarrow \infty} \frac{f(x)}{g(x)}=\infty$ or if $\lim _{x \rightarrow \infty} \frac{g(x)}{f(x)}=0$.

If $f(\mathrm{x})$ grows faster than $\mathrm{g}(\mathrm{x})$ as $\mathrm{x} \rightarrow \infty$, then $\mathrm{g}(\mathrm{x})$ grows slower than $f(\mathrm{x})$ as $x \rightarrow \infty$.
2. $f(\mathrm{x})$ and $\mathrm{g}(\mathrm{x})$ grow at the same rate as $\mathrm{x} \rightarrow \infty$ if $\lim _{\mathrm{x} \rightarrow \infty} \frac{f(\mathrm{x})}{\mathrm{g}(\mathrm{x})}=\mathrm{L} \neq 0$ (L is finite and nonzero).
For example,

1. $e^{\mathrm{x}}$ grows faster than $\mathrm{x}^{3}$ as $\mathrm{x} \rightarrow \infty$ since $\lim _{\mathrm{x} \rightarrow \infty} \frac{e^{\mathrm{x}}}{\mathrm{x}^{3}}=\infty$
2. $x^{4}$ grows faster than $\ln x$ as $x \rightarrow \infty$ since $\lim _{x \rightarrow \infty} \frac{x^{4}}{\ln x}=\infty$
3. $x^{2}+2 x$ grows at the same rate as $x^{2}$ as $x \rightarrow \infty$ since $\lim _{x \rightarrow \infty} \frac{x^{2}+2 x}{x^{2}}=1$

To find some of these limits as $x \rightarrow \infty$, you may use the graphing calculator. Make sure that an appropriate viewing window is used.
18.

L'Hôpital's Rule
If $\lim _{x \rightarrow a} \frac{f(x)}{g(x)}$ is of the form $\frac{0}{0}$ or $\frac{\infty}{\infty}$, and if $\lim _{x \rightarrow a} \frac{f^{\prime}(x)}{g^{\prime}(x)}$ exists, then $\lim _{x \rightarrow a} \frac{f(x)}{g(x)}=\lim _{x \rightarrow a} \frac{f^{\prime}(x)}{g^{\prime}(x)}$.
19. Inverse function

1. If $f$ and $g$ are two functions such that $f(g(x))=x$ for every $x$ in the domain of $g$ and $g(f(x))=x$ for every $x$ in the domain of $f$, then $f$ and $g$ are inverse functions of each other.
2. A function $f$ has an inverse if and only if no horizontal line intersects its graph more than once.
3. If $f$ is strictly either increasing or decreasing in an interval, then $f$ has an inverse.
4. If $f$ is differentiable at every point on an interval $I$, and $f^{\prime}(x) \neq 0$ on $I$, then
$g=f^{-1}(x)$ is differentiable at every point of the interior of the interval $f(I)$ and if the point $(a, b)$ is on $f(x)$, then the point $(b, a)$ is on $g=f^{-1}(x)$; furthermore $g^{\prime}(b)=\frac{1}{f^{\prime}(a)}$.
5. $\quad$ Properties of $y=e^{x}$
6. The exponential function $y=e^{x}$ is the inverse function of $y=\ln x$.

|  | $f(x)$ | $f^{-1}(x)$ |
| :--- | :--- | :--- |
| Point | $(a, b)$ | $(b, a)$ |
| Slope | $f^{\prime}(a)=k$ | $\left(f^{-1}\right)^{\prime}(b)=\frac{1}{k}$ |

2. The domain is the set of all real numbers,

$$
-\infty<x<\infty
$$

3. The range is the set of all positive numbers, $y>0$.
4. $\quad \frac{d}{d x}\left(e^{x}\right)=e^{x}$ and $\frac{d}{d x}\left(e^{f(x)}\right)=f^{\prime}(x) e^{f(x)}$
5. $e^{x_{1}} \cdot e^{x_{2}}=e^{x_{1}+x_{2}}$
6. $y=e^{x}$ is continuous, increasing, and concave up for all $x$.
7. $\lim _{x \rightarrow \infty} e^{x}=+\infty$ and $\lim _{x \rightarrow-\infty} e^{x}=0$.
8. $e^{\ln x}=x$, for $x>0 ; \ln \left(e^{x}\right)=x$ for all $x$.
9. Properties of $y=\ln x$
10. The domain of $y=\ln x$ is the set of all positive numbers, $x>0$.
11. The range of $y=\ln x$ is the set of all real numbers, $-\infty<y<\infty$.
12. $y=\ln x$ is continuous and increasing everywhere on its domain.
13. $\quad \ln (a b)=\ln a+\ln b .\{$ Very useful and necessary for derivatives.\}
14. $\ln \left(\frac{a}{b}\right)=\ln a-\ln b .\{$ Very useful and necessary for derivatives.\}
15. $\quad \ln a^{r}=r \ln a$. \{Very useful and necessary for derivatives.\}
16. $y=\ln x<0$ if $0<x<1$.
17. $\quad \lim _{x \rightarrow \infty} \ln x=+\infty$ and $\lim _{x \rightarrow 0^{+}} \ln x=-\infty$.
18. $\log _{a} x=\frac{\ln x}{\ln a}$
19. $\frac{d}{d x}(\ln f(x))=\frac{f^{\prime}(x)}{f(x)}$ and $\frac{d}{d x}(\ln (x))=\frac{1}{x}$
20. Trapezoidal Rule

If a function $f$ is continuous on the closed interval $[a, b]$ where $[a, b]$ has been equally
partitioned into $n$ subintervals $\left[x_{0}, x_{1}\right],\left[x_{1}, x_{2}\right], \ldots\left[x_{n-1}, x_{n}\right]$, each length $\frac{b-a}{n}$, then
$\int_{a}^{b} f(x) d x \approx \frac{b-a}{2 n}\left[f\left(x_{0}\right)+2 f\left(x_{1}\right)+2 f\left(x_{2}\right)+\ldots+2 f\left(x_{n-1}\right)+f\left(x_{n}\right)\right]$, which is
equivalent to $\frac{1}{2}($ Leftsum + Rightsum $)$
23a. Definition of Definite Integral as the Limit of a Sum
Suppose that a function $f(x)$ is continuous on the closed interval $[a, b]$. Divide the interval into $n$ equal subintervals, of length $\Delta x=\frac{b-a}{n}$. Choose one number in each subinterval, in other words, $x_{1}$ in the first, $x_{2}$ in the second, $\ldots, x_{k}$ in the $k$ th,$\ldots$, and $x_{n}$ in the $n$ th. Then $\lim _{n \rightarrow \infty} \sum_{k=1}^{n} f\left(x_{k}\right) \Delta x=\int_{a}^{b} f(x) d x=F(b)-F(a)$.

23b. Properties of the Definite Integral
Let $f(x)$ and $g(x)$ be continuous on $[a, b]$.
i). $\int_{a}^{b} c \cdot f(x) d x=c \int_{a}^{b} f(x) d x$ for any constant $c$.
ii). $\int_{a}^{a} f(x) d x=0$
iii). $\int_{a}^{b} f(x) d x=-\int_{b}^{a} f(x) d x$
iv). $\int_{a}^{b} f(x) d x=\int_{a}^{c} f(x) d x+\int_{c}^{b} f(x) d x$, where $f$ is continuous on an interval containing the numbers $a, b$, and $c$.
v). If $f(x)$ is an odd function, then $\int_{-a}^{a} f(x) d x=0$
vi). If $f(x)$ is an even function, then $\int_{-a}^{a} f(x) d x=2 \int_{0}^{a} f(x) d x$
vii). If $f(x) \geq 0$ on $[a, b]$, then $\int_{a}^{b} f(x) d x \geq 0$
viii). If $g(x) \geq f(x)$ on $[a, b]$, then $\int_{a}^{b} g(x) d x \geq \int_{a}^{b} f(x) d x$
24. Fundamental Theorem of Calculus:
$b$
$\int_{a}^{b} f(x) d x=F(b)-F(a)$, where $F^{\prime}(x)=f(x)$.

## 25. Second Fundamental Theorem of Calculus (Steve's Theorem):

$$
\frac{\mathrm{d}}{\mathrm{dx}} \int_{\mathrm{a}}^{\mathrm{x}} f(\mathrm{t}) \mathrm{dt}=f(\mathrm{x}) \quad \text { or } \quad \frac{\mathrm{d}}{\mathrm{dx}} \int_{\mathrm{h}(\mathrm{x})}^{\mathrm{g}(\mathrm{x})} f(\mathrm{t}) \mathrm{dt}=\mathrm{g}^{\prime}(\mathrm{x}) f(\mathrm{~g}(\mathrm{x}))-\mathrm{h}^{\prime}(\mathrm{x}) \mathrm{f}(\mathrm{~h}(\mathrm{x}))
$$

26. Velocity, Speed, and Acceleration
27. The velocity of an object tells how fast it is going and in which direction. Velocity is an instantaneous rate of change. If velocity is positive (graphically above the " $x$ "-axis), then the object is moving away from its point of origin. If velocity is negative (graphically below the " $x$ "-axis), then the object is moving back towards its point of origin. If velocity is 0 (graphically the point(s) where it hits the " $x$ "-axis), then the object is not moving at that time.
28. The speed of an object is the absolute value of the velocity, $|v(\mathrm{t})|$. It tells how fast it is going disregarding its direction.
The speed of a particle increases (speeds up) when the velocity and acceleration have the same signs. The speed decreases (slows down) when the velocity and acceleration have opposite signs.
29. The acceleration is the instantaneous rate of change of velocity - it is the derivative of the velocity - that is, $a(\mathrm{t})=v^{\prime}(\mathrm{t})$. Negative acceleration (deceleration) means that the velocity is decreasing (i.e. the velocity graph would be going down at that time), and vice-versa for acceleration increasing. The acceleration gives the rate at which the velocity is changing.

Therefore, if x is the displacement of a moving object and t is time, then:
i) velocity $=v(t)=x^{\prime}(t)=\frac{d x}{d t}$
ii) acceleration $=a(\mathrm{t})=\mathrm{x}^{\prime \prime}(\mathrm{t})=v^{\prime}(\mathrm{t})=\frac{\mathrm{dv}}{\mathrm{dt}}=\frac{\mathrm{d}^{2} \mathrm{x}}{\mathrm{dt}^{2}}$
iii) $v(\mathrm{t})=\int a(\mathrm{t}) \mathrm{dt}$
iv) $\mathrm{x}(\mathrm{t})=\int v(\mathrm{t}) \mathrm{dt}$

Note: The average velocity of a particle over the time interval from $t_{0}$ to another time $t$, is
Average Velocity $=\frac{\text { Change in position }}{\text { Length of time }}=\frac{s(t)-s\left(t_{0}\right)}{t-t_{0}}$, where $s(t)$ is the position of the particle at time t or $\frac{1}{b-a} \int_{a}^{b} v(t) d t$ if given the velocity function.
27. The average value of $f(x)$ on $[a, b]$ is $\frac{1}{b-a} \int_{a}^{b} f(x) d x$. (Note, this gives the Average of what is given - i.e. given velocity, this would find average velocity)
28. Area Between Curves

If $f$ and $g$ are continuous functions such that $f(x) \geq g(x)$ on $[a, b]$, then area between the curves is $\int_{a}^{b}[f(x)-g(x)] d x$ or $\int_{a}^{b}[$ top-bottom $] d x$ or $\int_{c}^{d}[$ right-left $] d y$.
29. $* * *$ Integration By "Parts"

If $u=f(x)$ and $v=g(x)$ and if $f^{\prime}(x)$ and $g^{\prime}(x)$ are continuous, then
$\int u d v=u v-\int v d u$.
Note: The goal of the procedure is to choose $u$ and $d v$ so that $\int v d u$ is easier to solve than the original problem.
Suggestion:
When "choosing" $u$, remember L.I.P.E.T, where $\mathbf{L}$ is the logarithmic function, $\mathbf{I}$ is an inverse trigonometric function, $\mathbf{P}$ is a polynomial function, $\mathbf{E}$ is the exponential function, and $\mathbf{T}$ is a trigonometric function. Just choose $u$ as the first expression in L.I.P.E.T (and $d v$ will be the remaining part of the integrand). For example, when integrating $\int x \ln x d x$, choose $u=\ln x$ since $\mathbf{L}$ comes first in L.I.P.E.T, and $d v=x d x$. When integrating $\int x e^{x} d x$, choose $u=x$, since $x$ is an algebraic function, and $\mathbf{A}$ comes before $\mathbf{E}$ in L.I.P.E.T, and $d v=e^{x} d x$. One more example, when integrating $\int x \operatorname{Arctan}(x) d x$, let $u=\operatorname{Arctan}(x)$, since $\mathbf{I}$ comes before A in L.I.P.E.T, and $d v=x d x$. \{Don't forget tabular form for parts when $u$ is a polynomial $\}$
30. Volume of Solids of Revolution (rectangles drawn perpendicular to the axis of revolution)

- Revolving around a horizontal line (y=\# or x-axis) where $a \leq x \leq b$ :

Axis of Revolution and the region being revolved:
$V=\pi \int_{a}^{b}(\text { furthest from a.r. }- \text { a.r. })^{2}-(\text { closest to a.r. }- \text { a.r. })^{2} d x$

- Revolving around a vertical line ( $x=\#$ or $y$-axis) where $c \leq y \leq d$ (or use Shell Method):

Axis of Revolution and the region being revolved:

$$
V=\pi \int_{c}^{d}(\text { furthest from a.r. }- \text { a.r. })^{2}-(\text { closest to a.r. }- \text { a.r. })^{2} d y
$$

30b. Volume of Solids with Known Cross Sections

1. For cross sections of area $A(x)$, taken perpendicular to the x-axis, volume $=\int_{a}^{b} A(x) d x$.

Cross-sections \{if only one function is used then just use that function, if it is between two functions use top-bottom if perpendicular to the x-axis or right-left if perpendicular to the y-axis\} mostly all the same only varying by a constant, with the only exception being the rectangular cross-sections:

- Square cross-sections:

$$
V=\int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Equilateral cross-sections:

$$
V=\frac{\sqrt{3}}{4} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Isosceles Right Triangle cross-sections (hypotenuse in the $x y$ plane):

$$
V=\frac{1}{4} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Isosceles Right Triangle cross-sections (leg in the $x y$ plane):

$$
V=\frac{1}{2} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Semi-circular cross-sections:

$$
V=\frac{\pi}{8} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Rectangular cross-sections (height function or value must be given or articulated somehow - notice no "square" on the $\{$ top - bottom $\}$ part):

$$
V=\int_{a}^{b}(\text { top function }- \text { bottom function }) \cdot(\text { height function or value }) d x
$$

- Circular cross-sections with the diameter in the $x y$ plane:

$$
V=\frac{\pi}{4} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

- Square cross-sections with the diagonal in the $x y$ plane:

$$
V=\frac{1}{2} \int_{a}^{b}(\text { top function }- \text { bottom function })^{2} d x
$$

2. For cross sections of area $A(y)$, taken perpendicular to the y-axis, volume $=\int_{a}^{b} A(y) d y$.

30c. $\quad * * *$ Shell Method (used if function is in terms of x and revolving around a vertical line) where $a \leq x \leq b:$ \{This is a concept not used in either AB or BC but may be handy for college ${ }_{\text {I }}$

$$
\begin{aligned}
& V=2 \pi \int_{a}^{b} r(x) h(x) d x \\
& r(x)=x \quad \text { if a.r. is y-axis }(x=0) \\
& r(x)=(x-a . r .) \quad \text { if a.r. is to the left of the region } \\
& r(x)=(\text { a.r. }-x) \quad \text { if a.r. is to the right of the region } \\
& h(x)=f(x) \text { if only revolving with one function } \\
& h(x)=(\text { top }- \text { bottom }) \quad \text { if revolving the region between two functions }
\end{aligned}
$$

31. Solving Differential Equations: Graphically and Numerically Slope Fields
At every point $(\mathrm{x}, \mathrm{y})$ a differential equation of the form $\frac{\mathrm{dy}}{\mathrm{dx}}=f(\mathrm{x}, \mathrm{y})$ gives the slope of the member of the family of solutions that contains that point. A slope field is a graphical representation of this family of curves. At each point in the plane, a short segment is drawn whose slope is equal to the value of the derivative at that point. These segments are tangent to the solution's graph at the point.

## Diff EQ Solutions:

1. Separate Variables
2. Integrate Both Sides ( +C on the independent variable side)
3. If $\ln$ on the dependent variable side, solve for $y$ first, then solve for $C$. If no $\ln$ on the dependent variable side, solve for C , then solve for $y$.

## ***Euler's Method (BC topic)

Euler's Method is a way of approximating points on the solution of a differential equation
$\frac{\mathrm{dy}}{\mathrm{dx}}=f(\mathrm{x}, \mathrm{y})$. The calculation uses the tangent line approximation to move from one point to the next. That is, starting with the given point $\left(\mathrm{x}_{1}, \mathrm{y}_{1}\right)$ - the initial condition, the point $\left(\mathrm{x}_{1}+\Delta \mathrm{x}, \mathrm{y}_{1}+f^{\prime}\left(\mathrm{x}_{1}, \mathrm{y}_{1}\right) \Delta \mathrm{x}\right)$ approximates a nearby point on the solution graph. This aproximation may then be used as the starting point to calculate a third point and so on. The accuracy of the method decreases with large values of $\Delta x$. The error increases as each successive point is used to find the next.

| $(x, y):$ given | $\frac{d y}{d x}:$ given | $\Delta x:$ given | $\Delta y=\frac{d y}{d x} \Delta x$ | $(x+\Delta x, y+\Delta y)$ |
| :--- | :--- | :--- | :--- | :--- |
| Start again |  |  |  |  |

## 32. $* * *$ Logistics ( $\mathbf{B C}$ topic)

1. Rate is jointly proportional to its size and the difference between a fixed positive number (L) and its size.

$$
\begin{aligned}
& \frac{d y}{d t}=k y\left(1-\frac{y}{L}\right) \text { OR } \frac{d y}{d t}=k y(M-y) \text { which yields } \\
& y=\frac{M}{1+C e^{-M k t}} \text { through separation of variables }
\end{aligned}
$$

2. $\lim _{t \rightarrow \infty} y=M ; M=$ carrying capacity (Maximum); horizontal asymptote
3. y-coordinate of inflection point is $\frac{\mathrm{L}}{2}$, i.e. when it is growing the fastest (or max rate).

32(a). *** Decomposition:
Steps:

1. Use Long Division first if the degree of the Numerator is equal or more than the Denominator to get $\int \frac{N(x)}{D(x)} d x=\int q(x) d x+\int \frac{r(x)}{D(x)} d x$
2. For the second integral, factor $D(x)$ completely into Linear factors to get

$$
\frac{r(x)}{D(x)}=\frac{A}{\text { linearfactor } \# 1}+\frac{B}{\text { linearfactor } \# 2}+\ldots
$$

3. Multiply both sides by $D(x)$ to eliminate the fractions
4. Choose your x -values wisely so that you can easily solve for $\mathrm{A}, \mathrm{B}, \mathrm{C}$, etc
5. Rewrite your integral that has been decomposed and integrate everything.

## 33. ****Definition of Arc Length

If the function given by $y=f(x)$ represents a smooth curve on the interval $[a, b]$, then the arc length of $f$ between $a$ and $b$ is given by $s=\int_{a}^{b} \sqrt{1+\left[f^{\prime}(x)\right]^{2}} d x$.
34. $* * *$ Improper Integral
$\int_{a}^{b} f(x) d x$ is an improper integral if

1. $f$ becomes infinite at one or more points of the interval of integration, or
2. one or both of the limits of integration is infinite, or
3. both (1) and (2) hold.
4. $\quad * * *$ Parametric Form of the Derivative

If a smooth curve $\mathbf{C}$ is given by the parametric equations $x=f(x)$ and $y=g(t)$, then the slope of the curve $\mathbf{C}$ at $(x, y)$ is $\frac{d y}{d x}=\frac{d y}{d t} \div \frac{d x}{d t}, \frac{d x}{d t} \neq 0$.
Note: The second derivative, $\frac{d^{2} y}{d x^{2}}=\frac{d}{d x}\left[\frac{d y}{d x}\right]=\frac{d}{d t}\left[\frac{d y}{d x}\right] \div \frac{d x}{d t}$.

## 36. $\quad * * *$ Arc Length in Parametric Form

If a smooth curve $\mathbf{C}$ is given by $x=f(t)$ and $y=g(t)$ and these functions have continuous first derivatives with respect to $t$ for $a \leq t \leq b$, and if the point $P(x, y)$ traces the curve exactly once as $t$ moves from $t=a$ to $t=b$, then the length of the curve is given by

$$
\begin{aligned}
& s=\int_{a}^{b} \sqrt{\left(\frac{d x}{d t}\right)^{2}+\left(\frac{d y}{d t}\right)^{2}} d t=\int_{a}^{b} \sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}} d t . \\
& \text { speed }=\sqrt{\left(\mathrm{f}^{\prime}(\mathrm{t})\right)^{2}+\left(\mathrm{g}^{\prime}(\mathrm{t})\right)^{2}}
\end{aligned}
$$

37. $* * *$ Vectors

Velocity, speed, acceleration, and direction of motion in Vector form

- position vector is $r(t)=\langle x(t), y(t)\rangle$
- velocity vector is $v(t)=\left\langle\frac{d x}{d t}, \frac{d y}{d t}\right\rangle$
- speed is the magnitude of velocity because speed $=|v(t)|=\sqrt{\left(\frac{d x}{d x}\right)^{2}+\left(\frac{d y}{d t}\right)^{2}}$
- acceleration vector is $a(t)=\left\langle\frac{d^{2} x}{d t^{2}}, \frac{d^{2} y}{d t^{2}}\right\rangle$
- the direction of motion is based on the velocity vector and the signs on its components Displacement and distance travelled in vector form
- Displacement in vector form $\left\langle\int_{a}^{b} v_{1}(t) d t, \int_{a}^{b} v_{2}(t) d t\right\rangle$
- Final position in vector form $\left(x_{1}(a)+\int_{a}^{b} v_{1}(t) d t, x_{2}(a)+\int_{a}^{b} v_{2}(t) d t\right)$
- Distance travelled from

$$
t=a \text { to } t=b \text { is given by } \int_{a}^{b}|v(t)| d t=\int_{a}^{b} \sqrt{\left(v_{1}(t)\right)^{2}+\left(v_{2}(t)\right)^{2}} d t
$$

38. $* * *$ Polar Coordinates
39. Cartesian vs. Polar Coordinates. The polar coordinates $(r, \theta)$ are related to the Cartesian coordinates $(x, y)$ as follows:

$$
x=r \cos \theta \text { and } y=r \sin \theta \quad \tan \theta=\frac{y}{x} \text { and } x^{2}+y^{2}=r^{2}
$$

2. To find the points of intersection of two polar curves, and solve for $\theta$. Check separately to see if the origin lies on both curves, i.e. if $r$ can be 0 . Sketch the curves.
3. Area in Polar Coordinates: If $f$ is continuous and nonnegative on the interval $[\alpha, \beta]$, then the area of the region bounded by the graph of $r=f(\theta)$ between the radial lines $\theta=\alpha$ and $\theta=\beta$ is given by

$$
A=\frac{1}{2} \int_{\alpha}^{\beta}(f(\theta))^{2} d \theta=\frac{1}{2} \int_{\alpha}^{\beta} r^{2} d \theta
$$

4. Derivative of Polar function: Given $\mathrm{r}=f(\theta)$, to find the derivative, use parametric equations.

$$
\mathrm{x}=\mathrm{r} \cos \theta=f(\theta) \cos \theta \quad \text { and } \quad \mathrm{y}=\mathrm{r} \sin \theta=f(\theta) \sin \theta
$$

$$
\text { Then } \frac{\mathrm{dy}}{\mathrm{dx}}=\frac{\mathrm{dy} / \mathrm{d} \theta}{\mathrm{dx} / \mathrm{d} \theta}=\frac{f(\theta) \cos \theta+f^{\prime}(\theta) \sin \theta}{-f(\theta) \sin \theta+f^{\prime}(\theta) \cos \theta}
$$

5. Arc Length in Polar Form: $\mathrm{s}=\int_{\alpha}^{\beta} \sqrt{\mathrm{r}^{2}+\left(\frac{\mathrm{dr}}{\mathrm{d} \theta}\right)^{2}} \mathrm{~d} \theta$
6. Area for a region inside $r_{1} \xrightarrow{\text { and outside }} r_{2}$ is $\frac{1}{2} \int_{\theta_{1}}^{\theta_{2}} r_{1}^{2}-r_{2}^{2} d \theta$
7. Area shared by two polar curves $r_{1}$ and $r_{2}$ is given by $\frac{1}{2} \int_{\theta_{1}}^{\theta_{2}} r_{1}^{2} d \theta+\frac{1}{2} \int_{\theta_{2}}^{\theta_{3}} r_{2}^{2} d \theta$ \{remember to use symmetry if able to \}
8. Increasing or decreasing: calculate $\frac{d r}{d \theta}$ and determine if it is positive or negative.
9. $* * *$ Sequences and Series
10. If a sequence $\left\{a_{n}\right\}$ has a limit $L$, that is, $\lim _{n \rightarrow \infty} a_{n}=L$, then the sequence is said to converge to $L$. If there is no limit, the series diverges. If the sequence $\left\{a_{n}\right\}$ converges, then its limit is unique. Keep in mind that
$\lim _{n \rightarrow \infty} \frac{\ln n}{n}=0 ; \quad \lim _{n \rightarrow \infty} x^{(1 / n)}=1 ; \quad \lim _{n \rightarrow \infty} \sqrt[n]{n}=1 ; \quad \lim _{n \rightarrow \infty} \frac{x^{n}}{n!}=0$. These limits are useful and arise frequently.
11. The harmonic series $\sum_{n=1}^{\infty} \frac{1}{n}$ diverges; the geometric series $\sum_{n=0}^{\infty} a r^{n}$ converges to $\frac{\text { first term by using the initial } n \text { value on the sigma }}{1-(\text { the "value" that has the power })}=\frac{a}{1-r} \quad$ if $|r|<1$ and diverges if $|r| \geq 1$ and $a \neq 0$.
12. The p-series $\sum_{n=1}^{\infty} \frac{1}{n^{p}}$ converges if $p>1$ and diverges if $p \leq 1$.
13. Limit Comparison Test: Let $\sum_{n=1}^{\infty} a_{n}$ and $\sum_{n=1}^{\infty} b_{n}$ be a series of nonnegative terms, with $a_{n} \neq 0$ for all sufficiently large $n$, and suppose that $\lim _{n \rightarrow \infty} \frac{b_{n}}{a_{n}}=c>0$. Then the two series either both converge or both diverge.
14. Alternating Series: Let $\sum_{n=1}^{\infty} a_{n}$ be a series such that
i) the series is alternating
ii) $\quad\left|a_{n+1}\right| \leq\left|a_{n}\right|$ for all $n$, and
iii) $\quad \lim _{n \rightarrow \infty} a_{n}=0$

Then the series converges.
Alternating Series Remainder (Error Bound): (This is used on an alternating series instead of the LaGrange Error Bound)The remainder $\mathrm{R}_{\mathrm{N}}$ is less than (or equal to) the first neglected term \{absolute value of the next term in the series that was not used\}

$$
\left|\mathrm{R}_{\mathrm{n}}\right| \leq\left|\mathrm{a}_{\mathrm{n}+1}\right|
$$

6. The $n$-th Term Test for Divergence: If $\lim _{\mathrm{n} \rightarrow \infty} \mathrm{a}_{\mathrm{n}} \neq 0$, then the series diverges.

Note that the converse is false, that is, if $\lim _{\mathrm{n} \rightarrow \infty} \mathrm{a}_{\mathrm{n}}=0$, the series may or may not converge.
7. A series $\sum a_{n}$ is $\underline{\text { absolutely convergent }}$ if the series $\sum\left|a_{n}\right|$ converges. If $\sum a_{n}$ converges, but $\sum\left|a_{n}\right|$ does not converge, then the series is conditionally convergent. Keep in mind that if $\sum_{n=1}^{\infty}\left|a_{n}\right|$ converges, then $\sum_{n=1}^{\infty} a_{n}$ converges.
8. Direct Comparison Test: If $0 \leq a_{n} \leq b_{n}$ for all sufficiently large $n$, and $\sum_{n=1}^{\infty} b_{n}$ converges, then $\sum_{n=1}^{\infty} a_{n}$ converges. If $\sum_{n=1}^{\infty} a_{n}$ diverges, then $\sum_{n=1}^{\infty} b_{n}$ diverges.
9. Integral Test: If $f(x)$ is a positive, continuous, and decreasing function on $[1, \infty)$ and let $a_{n}=f(n)$. Then the series $\sum_{n=1}^{\infty} a_{n}$ will converge if the improper integral $\int_{1}^{\infty} f(x) d x$ converges. If the improper integral $\int_{1}^{\infty} f(x) d x$ diverges, then the infinite series $\sum_{n=1}^{\infty} a_{n}$ diverges.
10. Ratio Test: Let $\sum a_{n}$ be a series with nonzero terms.
i) If $\lim _{n \rightarrow \infty}\left|\frac{a_{n+1}}{a_{n}}\right|<1$, then the series converges absolutely.
ii) If $\lim _{n \rightarrow \infty}\left|\frac{a_{n+1}}{a_{n}}\right|>1$, then the series is divergent.
iii) If $\lim _{n \rightarrow \infty}\left|\frac{a_{n+1}}{a_{n}}\right|=1$, then the test is inconclusive (and another test must be used).
11. Power Series: A power series is a series of the form
$\sum_{n=0}^{\infty} c_{n} x^{n}=c_{0}+c_{1} x+c_{2} x^{2}+\ldots+c_{n} x^{n}+\ldots$ or
$\sum_{n=0}^{\infty} c_{n}(x-a)^{n}=c_{0}+c_{1}(x-a)+c_{2}(x-a)^{2}+\ldots+c_{n}(x-a)^{n}+\ldots$ in which the center $a$ and the coefficients $c_{0}, c_{1}, c_{2}, \ldots, c_{n}, \ldots$ in the polynomial are constants. The set of all numbers $x$ for which the power series converges is called the interval of convergence.
12. Taylor Series: Let $f$ be a function with derivatives of all orders throughout some intervale containing $a$ as an interior point. Then the Taylor series generated by $f$ at $a$ is

$$
\sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!}(x-a)^{k}=f(a)+f^{\prime}(a)(x-a)+\frac{f^{\prime \prime}(a)}{2!}(x-a)^{2}+\ldots+\frac{f^{(n)}(a)}{n!}(x-a)^{n}+\ldots
$$

The remaining terms after the term containing the $n$th derivative can be expressed as a remainder to Taylor's Theorem:
$f(x)=f(a)+\sum_{1}^{n} f^{(n)}(a)(x-a)^{n}+R_{n}(x)$ where $R_{n}(x)$ is the remainder terms
Lagrange's form of the remainder: $\left|f(x)-P_{n}(x)\right|=\left|R_{n} x\right|=\frac{M}{(n+1)!}|(x-a)|^{n+1}$,
where $a<c<x$ and $M$ is found by finding $f^{(n+1)}$ and its max value on the interval of $[a, x]$
The series will converge for all values of $x$ for which the remainder approaches zero as $\mathrm{x} \rightarrow \infty$.
13. Frequently Used Series and their Interval of Convergence

$$
\begin{aligned}
& \frac{1}{1-x}=1+x+x^{2}+\ldots+x^{n}+\ldots=\sum_{n=0}^{\infty} x^{n},|x|<1 \\
& e^{x}=1+x+\frac{x^{2}}{2!}+\ldots+\frac{x^{n}}{n!}+\ldots=\sum_{n=0}^{\infty} \frac{x^{n}}{n!},|x|<\infty \\
& \sin x=x-\frac{x^{3}}{3!}+\frac{x^{5}}{5!}-\ldots+(-1)^{n} \frac{x^{2 n+1}}{(2 n+1)!}+\ldots=\sum_{n=0}^{\infty} \frac{(-1)^{n} x^{2 n+1}}{(2 n+1)!},|x|<\infty \\
& \cos x=1-\frac{x^{2}}{2!}+\frac{x^{4}}{4!}-\ldots+(-1)^{n} \frac{x^{2 n}}{(2 n)!}+\ldots=\sum_{n=0}^{\infty} \frac{(-1) x^{2 n}}{(2 n)!},|x|<\infty
\end{aligned}
$$

## 14. Interval of Convergence (IOC) and Radius of Convergence (ROC).

1. Apply the Ratio Test to $\lim _{n \rightarrow \infty} \frac{\left|a_{n+1}\right|}{\left|a_{n}\right|}$. If the answer is:
a. 0 , then the ROC is infinite so it converges for all $x$
b. $\quad \infty$, then the ROC is 0 , so it only converges at its center
c. |expression|, then the ROC is found by setting $\mid$ expression $\mid<1$ and getting it in the form $|x-a|<R$
d. To find the IOC, get $x$ by itself so that $-R+a<x<R+a$. Plug each endpoint in the original $a_{n}$ for $x$, simplify, and use a convergence test to see if the series converges. If it does, add the "equal to" part to the inequality.

