### AP CALCULUS AB and BC <u>Final Notes</u>

### **Differentiation Formulas**

1. 
$$\frac{d}{dx}(x^{n}) = nx^{n-1}$$
10. 
$$\frac{d}{dx}(\csc x) = -\csc x \cot x$$
2. 
$$\frac{d}{dx}(fg) = fg' + gf' Product rule$$
11. 
$$\frac{d}{dx}(e^{x}) = e^{x}$$
3. 
$$\frac{d}{dx}\left(\frac{f}{g}\right) = \frac{gf' - fg'}{g^{2}} Quotient rule$$
12. 
$$\frac{d}{dx}(a^{x}) = a^{x} \ln a$$
4. 
$$\frac{d}{dx}f(g(x)) = f'(g(x))g'(x) Chain rule$$
13. 
$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$
5. 
$$\frac{d}{dx}(\sin x) = \cos x$$
14. 
$$\frac{d}{dx}(Arc \sin x) = \frac{1}{\sqrt{1 - x^{2}}}$$
6. 
$$\frac{d}{dx}(\cos x) = -\sin x$$
15. 
$$\frac{d}{dx}(Arc \tan x) = \frac{1}{1 + x^{2}}$$
7. 
$$\frac{d}{dx}(\tan x) = \sec^{2} x$$
16. 
$$\frac{d}{dx}(Arc \sec x) = \frac{1}{|x|\sqrt{x^{2} - 1}}$$
8. 
$$\frac{d}{dx}(\cot x) = -\csc^{2} x$$
17. 
$$\frac{d}{dx}[c] = 0$$
9. 
$$\frac{d}{dx}(\sec x) = \sec x \tan x$$
18. 
$$\frac{d}{dx}[cf(x)] = cf'(x)$$

### **Integration Formulas**

1. 
$$\int a \, dx = ax + C$$
  
2.  $\int x^n \, dx = \frac{x^{n+1}}{n+1} + C, \ n \neq -1$   
3.  $\int \frac{1}{x} \, dx = \ln|x| + C \ \int \frac{du}{u} = \ln|u| + C \ \int \frac{f'(x)}{f(x)} \, dx = \ln|f(x)| + C \ \int \frac{k}{x} \, dx = k \ln|x| + C$   
4.  $\int e^x \, dx = e^x + C \ \int f'(x) e^{f(x)} \, dx = e^{f(x)} + C \ \int e^{kx} \, dx = \frac{1}{k} e^{kx} + C$  {Shortcut}  
5.  $\int a^x \, dx = \frac{a^x}{\ln a} + C \ \int a^u \, du = \frac{a^u}{\ln a} + C \ \int f'(x) a^{f(x)} \, dx = \frac{a^{f(x)}}{\ln a} + C$   
6.  $\int \ln x \, dx = x \ln x - x + C$   
7.  $\int \sin x \, dx = -\cos x + C$   
8.  $\int \cos x \, dx = \sin x + C$   
9.  $\int \tan x \, dx = \ln|\sec x| + C \ \text{or} \ -\ln|\cos x| + C$   
10.  $\int \cot x \, dx = \ln|\sin x| + C$ 

11. 
$$\int \sec x \, dx = \ln|\sec x + \tan x| + C$$
  
12. 
$$\int \csc x \, dx = -\ln|\csc x + \cot x| + C$$
  
13. 
$$\int \sec^2 x \, dx = \tan x + C$$
  
14. 
$$\int \sec x \tan x \, dx = \sec x + C$$
  
15. 
$$\int \csc^2 x \, dx = -\cot x + C$$
  
16. 
$$\int \csc x \cot x \, dx = -\csc x + C$$
  
17. 
$$\int \tan^2 x \, dx = \tan x - x + C$$
  
18. 
$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \frac{1}{a} \operatorname{Arc} \tan\left(\frac{x}{a}\right) + C$$
  
19. 
$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \operatorname{Arc} \sin\left(\frac{x}{a}\right) + C$$
  
20. 
$$\int \frac{dx}{x\sqrt{x^2 - a^2}} = \frac{1}{a} \operatorname{Arc} \sec\left|\frac{|x|}{a} + C = \frac{1}{a} \operatorname{Arc} \cos\left|\frac{a}{x}\right| + C$$
  
Shortcuts  
Shortcuts  

$$\int \sin(kx) \, dx = -\frac{1}{k} \cos(kx) + C$$
  

$$\int \sin(kx) \, dx = \frac{1}{k} \sin(kx) + C$$
  

$$\int \sec(kx) \, dx = \frac{1}{k} \tan(kx) + C$$
  

$$\int \sec(kx) \tan(kx) \, dx = \frac{1}{k} \sec(kx) + C$$
  

$$\int \operatorname{csc}(kx) \cot(kx) \, dx = -\frac{1}{k} \operatorname{csc}(kx) + C$$
  

$$\int \operatorname{csc}(kx) \, dx = -\frac{1}{k} \ln|\csc(kx)| + C = \frac{1}{k} \ln|\sec(kx)| + C$$
  

$$\int \sec(kx) \, dx = \frac{1}{k} \ln|\sec(kx) + \tan(kx)| + C$$
  

$$\int \operatorname{csc}(kx) \, dx = -\frac{1}{k} \ln|\sec(kx) + \tan(kx)| + C$$
  

$$\int \operatorname{csc}(kx) \, dx = -\frac{1}{k} \ln|\sec(kx) + \tan(kx)| + C$$
  

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$$\int \operatorname{csc}(kx) \, dx = \frac{1}{k} \ln|\sec(kx) + \cot(kx)| + C$$

### Formulas, Concepts, and Theorems

A function y = f(x) is <u>continuous</u> at x = a if

- i). f(a) exists
- ii).  $\lim_{x \to a} f(x)$  exists

iii). 
$$\lim_{x \to a} f(x) = f(a)$$

Otherwise, f is discontinuous at x = a.

The limit  $\lim_{x \to a} f(x)$  exists if and only if both corresponding one-sided limits exist and are equal – that is,

 $\lim_{\mathbf{x}\to\mathbf{a}} f(\mathbf{x}) = \mathbf{L} \to \lim_{\mathbf{x}\to\mathbf{a}^{+}} f(\mathbf{x}) = \mathbf{L} = \lim_{\mathbf{x}\to\mathbf{a}^{-}} f(\mathbf{x})$ 

### 2. <u>Even and Odd Functions</u>

- 1. A function y = f(x) is <u>even</u> if f(-x) = f(x) for every x in the function's domain. Every even function is symmetric about the y-axis.
- 2. A function y = f(x) is <u>odd</u> if f(-x) = -f(x) for every x in the function's domain. Every odd function is symmetric about the origin.

### 3. <u>Periodicity</u>

A function f(x) is periodic with period p(p > 0) if f(x + p) = f(x) for every value of x

Note: The period of the function 
$$y = A\sin(Bx+C)$$
 or  $y = A\cos(Bx+C)$  is  $\frac{2\pi}{|B|}$ .

The amplitude is |A|. The period of  $y = \tan x$  is  $\pi$ .

### 4. Intermediate-Value Theorem

A function y = f(x) that is continuous on a closed interval [a,b] takes on every value between f(a) and f(b).

<u>Note</u>: If f is continuous on [a,b] and f(a) and f(b) differ in sign, then the equation f(x) = 0 has at least one solution in the open interval (a,b).

### 5. **Limits of Rational Functions as** $x \to \pm \infty$

i).  $\lim_{x \to \pm \infty} \frac{f(x)}{g(x)} = 0 \text{ if the degree of } f(x) < \text{ the degree of } g(x)$  $\underbrace{Example:}_{x \to \infty} \lim_{x \to \infty} \frac{x^2 - 2x}{x^3 + 3} = 0$ 

ii). 
$$\lim_{x \to \pm \infty} \frac{f(x)}{g(x)}$$
 is infinite if the degrees of  $f(x) >$  the degree of  $g(x)$ 

Example: 
$$\lim_{x \to \infty} \frac{x^3 + 2x}{x^2 - 8} = \infty$$

iii).  $\lim_{x \to \pm \infty} \frac{f(x)}{g(x)}$  is finite if the degree of f(x) = the degree of g(x)

Example: 
$$\lim_{x \to \infty} \frac{2x^2 - 3x + 2}{10x - 5x^2} = -\frac{2}{5}$$

### 6. <u>Horizontal and Vertical Asymptotes</u>

1. A line y = b is a **horizontal asymptote** of the graph y = f(x) if either  $\lim_{x \to \infty} f(x) = b \text{ or } \lim_{x \to \infty} f(x) = b \text{ (Compare degrees of functions in fraction)}$ 

2. A line 
$$x = a$$
 is a vertical asymptote of the graph  $y = f(x)$  if either  

$$\lim_{x \to a^+} f(x) = \pm \infty \text{ or } \lim_{x \to a^-} f(x) = \pm \infty \text{ (Values that make the denominator 0 but not numerator)}$$

### 7. <u>Average and Instantaneous Rate of Change</u>

i). <u>Average Rate of Change</u>: If  $(x_0, y_0)$  and  $(x_1, y_1)$  are points on the graph of y = f(x), then the average rate of change of y with respect to x over the interval

$$\begin{bmatrix} x_0, x_1 \end{bmatrix} \text{ is } \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{y_1 - y_0}{x_1 - x_0} = \frac{\Delta y}{\Delta x}. \text{ (old fashioned way of finding slope)}$$

ii). <u>Instantaneous Rate of Change</u>: If  $(x_0, y_0)$  is a point on the graph of y = f(x), then the instantaneous rate of change of y with respect to x at  $x_0$  is  $f'(x_0)$ . {new fashioned way of finding slope}

### 8. <u>Definition of Derivative</u>

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
 or  $f'(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$ 

The latter definition of the derivative is the instantaneous rate of change of f(x) with respect to

x at x = a. {i.e. the slope at x = a }

## Geometrically, *the derivative of a function at a point is the slope of the tangent line to the graph of the function at that point.*

### 9. <u>The Number *e* as a limit \*\*\*BC only</u>

i). 
$$\lim_{n \to \infty} \left( 1 + \frac{1}{n} \right)^n = e$$

ii). 
$$\lim_{n \to 0} (1+n)^{1/n} = e$$

### 10. <u>Rolle's Theorem (this is a weak version of the MVT)</u>

If f is continuous on [a,b] and differentiable on (a,b) such that f(a) = f(b), then there is at least one number c in the open interval (a,b) such that f'(c) = 0.

### 11. <u>Mean Value Theorem</u>

If f is continuous on [a,b] and differentiable on (a,b), then there is at least one number c in f(b) = f(a)

(a,b) such that  $\frac{f(b)-f(a)}{b-a} = f'(c)$ .

### 12. <u>Extreme-Value Theorem</u>

If f is continuous on a closed interval [a,b], then f(x) has both a maximum and minimum on [a,b].

- 13. <u>Absolute Mins and Maxs</u>: To find the maximum and minimum values of a function y = f(x) on a CLOSED interval, locate
  - 1. the points where f'(x) is zero or where f'(x) fails to exist. {Must be within the given interval}
  - 2. the end points, if any, on the domain of f(x).
  - 3. Plug those values into f(x) to see which gives you the max and which gives you this min values (the x-value is where that value occurs)

<u>Note</u>: These are the <u>only</u> candidates for the value of x where f(x) may have a maximum or a minimum.

### 14. Increasing and Decreasing:

- 1. If f'(x) > 0 for every x in (a,b), then f is increasing on [a,b].
- 2. If f'(x) < 0 for every x in (a,b), then f is decreasing on [a,b].

### **Relative mins and maxs:**

- 1. Relative Max if f' switches from positive to negative at x = a, then (a, f(a)) is a relative max of f.
- 2. Relative Min if f 'switches from negative to positive at x = a, then (a, f(a)) is a relative min of f.

### 15. Concavity:

- 1. If f''(x) > 0 in (a,b),  $\{f' \text{ is increasing}\}$  then f is concave upward in (a,b).
- 2. If f''(x) < 0 in (a,b),  $\{f' \text{ is decreasing}\}$  then f is concave downward in (a,b). To locate the <u>points of inflection</u> of y = f(x), find the points where f''(x) = 0 or where f''(x) fails to exist {or the x-values where f' has mins and maxs}. These are the only candidates where f(x) may have a point of inflection. Then test these points to make sure that f''(x) < 0 on one side and f''(x) > 0 on the other.
- 16a. **Differentiability and Continuity Theorem:** If a function is differentiable at point x = a, it is continuous at that point. The converse is false, in other words, continuity does <u>not</u> imply differentiability.

### 16b. Local Linearity and Linear Approximations {aka "Tangent lines"}

The linear approximation to f(x) near  $x = x_0$  is given by  $y = f(x_0) + f'(x_0)(x - x_0)$  for x sufficiently close to  $x_0$ . In other words, find the equation of the tangent line at  $(x_0, f(x_0))$ and use that equation to approximate the value at the value you need an estimate for.

### 17. \*\*\* Dominance and Comparison of Rates of Change (BC topic only)

Logarithm functions grow slower than any power function  $(x^n)$ .

Among power functions, those with higher powers grow faster than those with lower powers. All power functions grow slower than any exponential function  $(a^x, a > 1)$ .

Among exponential functions, those with larger bases grow faster than those with smaller bases. We say, that as  $x \to \infty$ :

1. f(x) grows <u>faster</u> than g(x) if  $\lim_{x \to \infty} \frac{f(x)}{g(x)} = \infty$  or if  $\lim_{x \to \infty} \frac{g(x)}{f(x)} = 0$ .

If f(x) grows faster than g(x) as  $x \to \infty$ , then g(x) grows <u>slower</u> than f(x) as  $x \to \infty$ .

2. f(x) and g(x) grow at the <u>same</u> rate as  $x \to \infty$  if  $\lim_{x \to \infty} \frac{f(x)}{g(x)} = L \neq 0$  (L is finite

and nonzero).

For example,

1. 
$$e^x$$
 grows faster than  $x^3$  as  $x \to \infty$  since  $\lim_{x \to \infty} \frac{e^x}{x^3} = \infty$   
2.  $x^4$  grows faster than  $\ln x$  as  $x \to \infty$  since  $\lim_{x \to \infty} \frac{x^4}{\ln x} = \infty$ 

3. 
$$x^2 + 2x$$
 grows at the same rate as  $x^2$  as  $x \to \infty$  since  $\lim_{x \to \infty} \frac{x^2 + 2x}{x^2} = 1$ 

To find some of these limits as  $x \to \infty$ , you may use the graphing calculator. Make sure that an appropriate viewing window is used.

### 18. <u>L'Hôpital's Rule</u>

If 
$$\lim_{x \to a} \frac{f(x)}{g(x)}$$
 is of the form  $\frac{0}{0}$  or  $\frac{\infty}{\infty}$ , and if  $\lim_{x \to a} \frac{f'(x)}{g'(x)}$  exists, then  $\lim_{x \to a} \frac{f(x)}{g(x)} = \lim_{x \to a} \frac{f'(x)}{g'(x)}$ 

### 19. Inverse function

- 1. If f and g are two functions such that f(g(x)) = x for every x in the domain of g and g(f(x)) = x for every x in the domain of f, then f and g are inverse functions of each other.
- 2. A function f has an inverse if and only if no horizontal line intersects its graph more than once.
- 3. If f is strictly either increasing or decreasing in an interval, then f has an inverse.
- 4. If f is differentiable at every point on an interval I, and  $f'(x) \neq 0$  on I, then

 $g = f^{-1}(x)$  is differentiable at every point of the interior of the interval f(I) and if the point (a,b) is on f(x), then the point (b,a) is on  $g = f^{-1}(x)$ ; furthermore

$$g'(b) = \frac{1}{f'(a)}$$

### 20. **Properties of** $y = e^{x}$

- 1. The exponential function  $y = e^{x}$  is the inverse function of  $y = \ln x$ .
- 2. The domain is the set of all real numbers,  $-\infty < x < \infty$ .
- 3. The range is the set of all positive numbers, y > 0.

4. 
$$\frac{d}{dx}(e^{x}) = e^{x} \text{ and } \frac{d}{dx}\left(e^{f(x)}\right) = f'(x)e^{f(x)}$$

5. 
$$e^{x_1} \cdot e^{x_2} = e^{x_1 + x_2}$$

6.  $y = e^{x}$  is continuous, increasing, and concave up for all x.

7. 
$$\lim_{x \to \infty} e^x = +\infty$$
 and  $\lim_{x \to -\infty} e^x = 0$ .

8. 
$$e^{\ln x} = x$$
, for  $x > 0$ ;  $\ln(e^x) = x$  for all  $x$ .

f(x) $f^{-1}(x)$ Point(a,b)(b,a)Slopef'(a) = k $(f^{-1})'(b) = \frac{1}{k}$ 

#### 21. **<u>Properties of</u>** $y = \ln x$

- The domain of  $y = \ln x$  is the set of all positive numbers, x > 0. 1.
- 2. The range of  $y = \ln x$  is the set of all real numbers,  $-\infty < y < \infty$ .
- $y = \ln x$  is continuous and increasing everywhere on its domain. 3.
- $\ln(ab) = \ln a + \ln b$ . {Very useful and necessary for derivatives.} 4.
- $\ln\left(\frac{a}{b}\right) = \ln a \ln b$ . {Very useful and necessary for derivatives.} 5.
- $\ln a^r = r \ln a$ . {Very useful and necessary for derivatives.} 6.
- $y = \ln x < 0$  if 0 < x < 1. 7.
- $\lim_{x\to\infty} \ln x = +\infty \text{ and } \lim_{x\to 0^+} \ln x = -\infty.$ 8.
- $\log_a x = \frac{\ln x}{\ln a}$ 9.  $\frac{d}{dx}(\ln f(x)) = \frac{f'(x)}{f(x)} \text{ and } \frac{d}{dx}(\ln(x)) = \frac{1}{x}$ 10.

#### 22. **Trapezoidal Rule**

If a function f is continuous on the closed interval [a,b] where [a,b] has been <u>equally</u> partitioned into *n* subintervals  $[x_0, x_1], [x_1, x_2], ... [x_{n-1}, x_{n-1}]$ , each length  $\frac{b-a}{a}$ , then

$$\int_{a}^{b} f(x) dx \approx \frac{b-a}{2n} \Big[ f(x_0) + 2f(x_1) + 2f(x_2) + \dots + 2f(x_{n-1}) + f(x_n) \Big], \text{ which is}$$
equivalent to  $\frac{1}{2} \big( \text{Leftsum} + \text{Rightsum} \big)$ 

#### 23a. Definition of Definite Integral as the Limit of a Sum

Suppose that a function f(x) is continuous on the closed interval [a,b]. Divide the interval into *n* equal subintervals, of length  $\Delta x = \frac{b-a}{n}$ . Choose one number in each subinterval, in other words,  $x_1$  in the first,  $x_2$  in the second, ...,  $x_k$  in the k th ,..., and  $x_n$  in the n th. Then  $\lim_{n\to\infty}\sum_{k=1}^{n}f(x_{k})\Delta x=\int_{0}^{b}f(x)dx=F(b)-F(a).$ 

#### **Properties of the Definite Integral** 23b.

Let f(x) and g(x) be continuous on [a,b]. i).  $\int_{a}^{b} c \cdot f(x) dx = c \int_{a}^{b} f(x) dx$  for any constant c. ii).  $\int_{a}^{a} f(x) \, dx = 0$ iii).  $\int_{a}^{b} f(x) dx = -\int_{b}^{a} f(x) dx$ iv).  $\int_{-\infty}^{b} f(x) dx = \int_{-\infty}^{c} f(x) dx + \int_{-\infty}^{b} f(x) dx$ , where f is continuous on an interval

containing the numbers a, b, and c.

v). If 
$$f(x)$$
 is an odd function, then  $\int_{-a}^{a} f(x) dx = 0$   
vi). If  $f(x)$  is an even function, then  $\int_{-a}^{a} f(x) dx = 2 \int_{0}^{a} f(x) dx$   
vii). If  $f(x) \ge 0$  on  $[a,b]$ , then  $\int_{a}^{b} f(x) dx \ge 0$   
viii). If  $g(x) \ge f(x)$  on  $[a,b]$ , then  $\int_{a}^{b} g(x) dx \ge \int_{a}^{b} f(x) dx$ 

24. **<u>Fundamental Theorem of Calculus:</u>**  $\int_{a}^{b} f(x) dx = F(b) - F(a)$ , where F'(x) = f(x).

### 25. <u>Second Fundamental Theorem of Calculus (Steve's Theorem)</u>:

$$\frac{d}{dx}\int_{a}^{x} f(t) dt = f(x) \quad \text{or} \quad \frac{d}{dx}\int_{h(x)}^{g(x)} f(t) dt = g'(x)f(g(x)) - h'(x)f(h(x))$$

- 26. Velocity, Speed, and Acceleration
  - 1. The <u>velocity</u> of an object tells how fast it is going and in which direction. Velocity is an instantaneous rate of change. If velocity is positive (graphically above the "x"-axis), then the object is moving away from its point of origin. If velocity is negative (graphically below the "x"-axis), then the object is moving back towards its point of origin. If velocity is 0 (graphically the point(s) where it hits the "x"-axis), then the object is not moving at that time.
  - 2. The <u>speed</u> of an object is the absolute value of the velocity, |v(t)|. It tells how fast it is going disregarding its direction.

The speed of a particle <u>increases</u> (speeds up) when the velocity and acceleration have the same signs. The speed <u>decreases</u> (slows down) when the velocity and acceleration have opposite signs.

3. The acceleration is the instantaneous rate of change of velocity – it is the derivative of the velocity – that is, a(t) = v'(t). Negative acceleration (deceleration) means that the velocity is decreasing (i.e. the velocity graph would be going down at that time), and vice-versa for acceleration increasing. The acceleration gives the rate at which the velocity is changing.

Therefore, if x is the displacement of a moving object and t is time, then:

i) velocity = 
$$v(t) = x'(t) = \frac{dx}{dt}$$
  
ii) acceleration =  $a(t) = x''(t) = v'(t) = \frac{dv}{dt} = \frac{d^2x}{dt^2}$   
iii)  $v(t) = \int a(t)dt$   
iv)  $x(t) = \int v(t)dt$ 

*Note:* The <u>average</u> velocity of a particle over the time interval from  $t_0$  to another time t, is Average Velocity =  $\frac{\text{Change in position}}{\text{Length of time}} = \frac{s(t) - s(t_0)}{t - t_0}$ , where s(t) is the position of the particle at time t or  $\frac{1}{b-a} \int_{a}^{b} v(t) dt$  if given the velocity function.

27. The average value of 
$$f(x)$$
 on  $[a,b]$  is  $\frac{1}{b-a} \int_{a}^{b} f(x) dx$ . (Note, this gives the Average of

what is given -i.e. given velocity, this would find average velocity)

28. <u>Area Between Curves</u>

If f and g are continuous functions such that  $f(x) \ge g(x)$  on [a,b], then area between the curves is  $\int_{a}^{b} [f(x) - g(x)] dx$  or  $\int_{a}^{b} [top - bottom] dx$  or  $\int_{c}^{d} [right - left] dy$ . \*\*\*<u>Integration By "Parts"</u> If u = f(x) and v = g(x) and if f'(x) and g'(x) are continuous, then  $\int u dv = uv - \int v du$ . <u>Note</u>: The goal of the procedure is to choose u and dv so that  $\int v du$  is easier to solve

<u>*Note*</u>. The goal of the procedure is to choose u and uv so that  $\int v du$  is easier than the original problem.

### Suggestion:

29.

When "choosing" u, remember **L.I.P.E.T**, where **L** is the logarithmic function, **I** is an inverse trigonometric function, **P** is a polynomial function, **E** is the exponential function, and **T** is a trigonometric function. Just choose u as the first expression in **L.I.P.E.T** (and dv will be the remaining part of the integrand). For example, when integrating  $\int x \ln x \, dx$ , choose  $u = \ln x$  since **L** comes first in **L.I.P.E.T**, and  $dv = x \, dx$ . When integrating  $\int xe^{x} \, dx$ , choose u = x, since x is an algebraic function, and **A** comes before **E** in **L.I.P.E.T**, and  $dv = e^{x} \, dx$ . One more example, when integrating  $\int x \, Arc \tan(x) \, dx$ , let  $u = Arc \tan(x)$ , since **I** comes before **A** in **L.I.P.E.T**, and  $dv = x \, dx$ . {Don't forget tabular form for parts when u is a polynomial}

### 30. <u>Volume of Solids of Revolution</u> (rectangles drawn perpendicular to the axis of revolution)

• Revolving around a horizontal line (y=# or x-axis) where  $a \le x \le b$ : Axis of Revolution and the region being revolved:

$$V = \pi \int_{a}^{b} (furthest from a.r. - a.r.)^{2} - (closest to a.r. - a.r.)^{2} dx$$

• Revolving around a vertical line (x=# or y-axis) where  $c \le y \le d$  (or use Shell Method): Axis of Revolution and the region being revolved:

$$V = \pi \int_{a}^{a} (furthest from a.r. - a.r.)^{2} - (closest to a.r. - a.r.)^{2} dy$$

### 30b. Volume of Solids with Known Cross Sections

1. For cross sections of area A(x), taken perpendicular to the x-axis, volume =  $\int A(x) dx$ .

**Cross-sections** {if only one function is used then just use that function, if it is between two functions use *top-bottom if perpendicular to the x-axis or right-left if perpendicular to the y-axis*} mostly all the same only varying by a constant, with the only exception being the rectangular cross-sections:

• Square cross-sections:

$$V = \int_{a}^{b} (top \ function - bottom \ function)^2 \ dx$$

• Equilateral cross-sections:

$$V = \frac{\sqrt{3}}{4} \int_{a}^{b} (top \ function - bottom \ function)^{2} \ dx$$

- Isosceles Right Triangle cross-sections (hypotenuse in the xy plane):  $V = \frac{1}{4} \int_{a}^{b} (top \ function - bottom \ function)^{2} dx$
- Isosceles Right Triangle cross-sections (leg in the *xy* plane):

$$V = \frac{1}{2} \int_{a}^{b} (top \ function - bottom \ function)^{2} \ dx$$

Semi-circular cross-sections:

$$V = \frac{\pi}{8} \int_{a}^{b} (top \ function - bottom \ function)^{2} \ dx$$

Rectangular cross-sections (height function or value must be given or articulated somehow – notice no "square" on the {top – bottom} part):

$$V = \int_{a}^{b} (top \ function - bottom \ function) \cdot (height \ function \ or \ value) dx$$

• Circular cross-sections with the diameter in the *xy* plane:

$$V = \frac{\pi}{4} \int_{a}^{b} (top \ function - bottom \ function)^{2} \ dx$$

- Square cross-sections with the diagonal in the xy plane:  $V = \frac{1}{2} \int (top \ function - bottom \ function)^2 \ dx$
- 2. For cross sections of area A(y), taken perpendicular to the y-axis, volume =  $\int_{a}^{b} A(y) dy$ .

30c. **\*\*\*Shell Method** (used if function is in terms of x and revolving around a vertical line) where  $a \le x \le b$ : {*This is a concept not used in either AB or BC but may be handy for college*}

 $V = 2\pi \int_{a}^{b} r(x)h(x)dx$   $r(x) = x \quad \text{if a.r. is y-axis } (x = 0)$   $r(x) = (x - a.r.) \quad \text{if a.r. is to the left of the region}$   $r(x) = (a.r. - x) \quad \text{if a.r. is to the right of the region}$   $h(x) = f(x) \quad \text{if only revolving with one function}$  $h(x) = (top - bottom) \quad \text{if revolving the region between two functions}$ 

### 31. <u>Solving Differential Equations: Graphically and Numerically</u> <u>Slope Fields</u>

At every point (x, y) a differential equation of the form  $\frac{dy}{dx} = f(x, y)$  gives the slope of the

member of the family of solutions that contains that point. A slope field is a graphical representation of this family of curves. At each point in the plane, a short segment is drawn whose slope is equal to the value of the derivative at that point. These segments are tangent to the solution's graph at the point.

### **Diff EQ Solutions:**

- 1. Separate Variables
- 2. Integrate Both Sides (+C on the independent variable side)
- 3. If  $\ln$  on the dependent variable side, solve for y first, then solve for C. If no  $\ln$  on the dependent variable side, solve for C, then solve for y.

### \*\*\*Euler's Method (BC topic)

Euler's Method is a way of approximating points on the solution of a differential equation

 $\frac{dy}{dx} = f(x, y)$ . The calculation uses the tangent line approximation to move from one point to the

next. That is, starting with the given point  $(x_1, y_1)$  – the initial condition, the point

 $(x_1 + \Delta x, y_1 + f'(x_1, y_1)\Delta x)$  approximates a nearby point on the solution graph. This

aproximation may then be used as the starting point to calculate a third point and so on. The accuracy of the method decreases with large values of  $\Delta x$ . The error increases as each successive point is used to find the next.

(x, y): given	$\frac{dy}{dx}$ : given	$\Delta x$ : given	$\Delta y = \frac{dy}{dx} \Delta x$	$(x + \Delta x, y + \Delta y)$
Start again				

### 32. \*\*\*<u>Logistics (BC topic)</u>

1. Rate is jointly proportional to its size and the difference between a fixed positive number (L) and its size.

$$\frac{dy}{dt} = ky\left(1 - \frac{y}{L}\right) \text{ OR } \frac{dy}{dt} = ky\left(M - y\right) \text{ which yields}$$

$$y = \frac{M}{1 + Ce^{-Mkt}}$$
 through separation of variables

- 2.  $\lim_{t \to \infty} y = M$ ; M = carrying capacity (Maximum); horizontal asymptote
- 3. y-coordinate of inflection point is  $\frac{L}{2}$ , i.e. when it is growing the fastest (or max rate).

### 32(a). \*\*\*<u>Decomposition</u>:

Steps: 1. Use Long Division first if the degree of the Numerator is equal or more than the Denominator

to get 
$$\int \frac{N(x)}{D(x)} dx = \int q(x) dx + \int \frac{r(x)}{D(x)} dx$$

2. For the second integral, factor D(x) completely into Linear factors to get

$$\frac{r(x)}{D(x)} = \frac{A}{linear factor \#1} + \frac{B}{linear factor \#2} + \dots$$

- 3. Multiply both sides by D(x) to eliminate the fractions
- 4. Choose your x-values wisely so that you can easily solve for A, B, C, etc
- 5. Rewrite your integral that has been decomposed and integrate everything.

### 33. \*\*\*Definition of Arc Length

If the function given by y = f(x) represents a smooth curve on the interval [a,b], then the arc

length of f between a and b is given by 
$$s = \int_{a}^{b} \sqrt{1 + [f'(x)]^2} dx$$
.

### 34. \*\*\*Improper Integral

 $\int_{a}^{b} f(x) dx$  is an improper integral if a

- 1. f becomes infinite at one or more points of the interval of integration, or
- 2. one or both of the limits of integration is infinite, or
- 3. both (1) and (2) hold.

### 35. \*\*\*Parametric Form of the Derivative

If a smooth curve **C** is given by the parametric equations x = f(x) and y = g(t), then the slope of the curve **C** at (x, y) is  $\frac{dy}{dx} = \frac{dy}{dt} \div \frac{dx}{dt}, \frac{dx}{dt} \neq 0$ .

# <u>Note</u>: The second derivative, $\frac{d^2 y}{dx^2} = \frac{d}{dx} \left[ \frac{dy}{dx} \right] = \frac{d}{dt} \left[ \frac{dy}{dx} \right] \div \frac{dx}{dt}$ .

### 36. \*\*\*<u>Arc Length in Parametric Form</u>

If a smooth curve C is given by x = f(t) and y = g(t) and these functions have continuous first derivatives with respect to t for  $a \le t \le b$ , and if the point P(x, y) traces the curve exactly once as t moves from t = a to t = b, then the length of the curve is given by

$$s = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} dt} = \int_{a}^{b} \sqrt{\left(f'(t)\right)^{2} + \left(g'(t)\right)^{2}} dt$$
  
speed =  $\sqrt{\left(f'(t)\right)^{2} + \left(g'(t)\right)^{2}}$ 

### 37. \*\*\*<u>Vectors</u>

Velocity, speed, acceleration, and direction of motion in Vector form

- position vector is  $r(t) = \langle x(t), y(t) \rangle$
- velocity vector is  $v(t) = \left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle$

• speed is the magnitude of velocity because  $speed = |v(t)| = \sqrt{\left(\frac{dx}{dx}\right)^2 + \left(\frac{dy}{dt}\right)^2}$ 

• acceleration vector is 
$$a(t) = \left\langle \frac{d^2x}{dt^2}, \frac{d^2y}{dt^2} \right\rangle$$

• the direction of motion is based on the velocity vector and the signs on its components Displacement and distance travelled in vector form

• Displacement in vector form 
$$\left\langle \int_{a}^{b} v_{1}(t) dt, \int_{a}^{b} v_{2}(t) dt \right\rangle$$
  
• Final position in vector form  $\left( x_{1}(a) + \int_{a}^{b} v_{1}(t) dt, x_{2}(a) + \int_{a}^{b} v_{2}(t) dt \right)$ 

• Distance travelled from

$$t = a$$
 to  $t = b$  is given by  $\int_{a}^{b} |v(t)| dt = \int_{a}^{b} \sqrt{(v_1(t))^2 + (v_2(t))^2} dt$ 

### 38. \*\*\*Polar Coordinates

1. <u>Cartesian vs. Polar Coordinates</u>. The polar coordinates  $(r, \theta)$  are related to the Cartesian coordinates (x, y) as follows:

$$x = r\cos\theta$$
 and  $y = r\sin\theta$   $\tan\theta = \frac{y}{x}$  and  $x^2 + y^2 = r^2$ 

- 2. To find the points of intersection of two polar curves, and solve for  $\theta$ . Check separately to see if the origin lies on both curves, i.e. if *r* can be 0. Sketch the curves.
- 3. <u>Area in Polar Coordinates</u>: If f is continuous and nonnegative on the interval  $[\alpha, \beta]$ , then the area of the region bounded by the graph of  $r = f(\theta)$  between the radial lines  $\theta = \alpha$  and  $\theta = \beta$  is given by

$$A = \frac{1}{2} \int_{\alpha}^{\beta} \left( f\left(\theta\right) \right)^{2} d\theta = \frac{1}{2} \int_{\alpha}^{\beta} r^{2} d\theta$$

**Derivative of Polar function**: Given  $\mathbf{r} = f(\theta)$ , to find the derivative, use parametric 4. equations.

$$\mathbf{x} = \mathbf{r}\cos\theta = f(\theta)\cos\theta$$
 and  $\mathbf{y} = \mathbf{r}\sin\theta = f(\theta)\sin\theta$ .

Then 
$$\frac{dy}{dx} = \frac{\frac{dy}{d\theta}}{\frac{dx}{d\theta}} = \frac{f(\theta)\cos\theta + f'(\theta)\sin\theta}{-f(\theta)\sin\theta + f'(\theta)\cos\theta}$$

5. Arc Length in Polar Form: 
$$s = \int_{\alpha}^{\beta} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$$

6. Area for a region inside 
$$r_1$$
 and outside  $r_2$  is  $\frac{1}{2} \int_{\theta_1}^{\theta_2} r_1^2 - r_2^2 d\theta$ 

7. <u>Area shared by two polar curves</u>  $r_1 \text{ and } r_2$  is given by  $\frac{1}{2} \int_{\theta}^{\theta_2} r_1^2 d\theta + \frac{1}{2} \int_{\theta}^{\theta_3} r_2^2 d\theta$  {remember to use symmetry if able to }

8. <u>Increasing or decreasing:</u> calculate  $\frac{dr}{d\theta}$  and determine if it is positive or negative.

### 39.

\*\*\*<u>Sequences and Series</u> 1. If a sequence  $\{a_n\}$  has a limit L, that is,  $\lim_{n \to \infty} a_n = L$ , then the sequence is said to <u>converge</u> to L. If there is no limit, the series <u>diverges</u>. If the sequence  $\{a_n\}$  converges, then its limit is unique. Keep in mind that

$$\lim_{n \to \infty} \frac{\ln n}{n} = 0; \quad \lim_{n \to \infty} x^{(1/n)} = 1; \quad \lim_{n \to \infty} \sqrt[n]{n} = 1; \quad \lim_{n \to \infty} \frac{x^n}{n!} = 0.$$
 These limits are useful and arise frequently.

are useful and arise frequently. 2. The <u>harmonic series</u>  $\sum_{n=1}^{\infty} \frac{1}{n}$  diverges; the <u>geometric series</u>  $\sum_{n=0}^{\infty} ar^n$  converges to  $\frac{\text{first term by using the initial } n \text{ value on the sigma}}{1 - (\text{the "value" that has the power})} = \frac{a}{1 - r} \text{ if } |r| < 1 \text{ and}$ diverges if  $|r| \ge 1$  and  $a \ne 0$ .

3. The **p-series** 
$$\sum_{n=1}^{\infty} \frac{1}{n^p}$$
 converges if  $p > 1$  and diverges if  $p \le 1$ 

4. <u>Limit Comparison Test</u>: Let  $\sum_{n=1}^{\infty} a_n$  and  $\sum_{n=1}^{\infty} b_n$  be a series of nonnegative terms, with

 $a_n \neq 0$  for all sufficiently large *n*, and suppose that  $\lim_{n \to \infty} \frac{b_n}{a_n} = c > 0$ . Then the two

series either both converge or both diverge.

- 5. <u>Alternating Series</u>: Let  $\sum_{n=1}^{\infty} a_n$  be a series such that
  - i) the series is alternating
  - ii)  $\left| a_{n+1} \right| \le \left| a_n \right|$  for all n, and
  - iii)  $\lim_{n \to \infty} a_n = 0$

Then the series converges.

<u>Alternating Series Remainder (Error Bound)</u>: (This is used on an alternating series instead of the LaGrange Error Bound)The remainder  $R_N$  is less than (or equal to) the first neglected term {absolute value of the next term in the series that was not used}

$$|\mathbf{R}_n| \leq |\mathbf{a}_{n+1}|$$

6. <u>The *n*-th Term Test for Divergence</u>: If  $\lim_{n \to \infty} a_n \neq 0$ , then the series diverges. Note that the converse is *false*, that is, if  $\lim_{n \to \infty} a_n = 0$ , the series may or may not converge.

- 7. A series  $\sum a_n$  is **absolutely convergent** if the series  $\sum |a_n|$  converges. If  $\sum a_n$  converges, but  $\sum |a_n|$  does not converge, then the series is <u>conditionally convergent</u>. Keep in mind that if  $\sum_{n=1}^{\infty} |a_n|$  converges, then  $\sum_{n=1}^{\infty} a_n$  converges.
- 8. <u>Direct Comparison Test</u>: If  $0 \le a_n \le b_n$  for all sufficiently large n, and  $\sum_{n=1}^{\infty} b_n$

converges, then 
$$\sum_{n=1}^{\infty} a_n$$
 converges. If  $\sum_{n=1}^{\infty} a_n$  diverges, then  $\sum_{n=1}^{\infty} b_n$  diverges.

9. Integral Test: If f(x) is a positive, continuous, and decreasing function on  $[1,\infty)$  and let  $a_n = f(n)$ . Then the series  $\sum_{n=1}^{\infty} a_n$  will converge if the improper integral  $\int_{1}^{\infty} f(x) dx$  converges. If the improper integral  $\int_{1}^{\infty} f(x) dx$  diverges, then the infinite series  $\sum_{n=1}^{\infty} a_n$  diverges.

- 10. **<u>Ratio Test</u>**: Let  $\sum a_n$  be a series with nonzero terms.
  - i) If  $\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| < 1$ , then the series converges absolutely. ii) If  $\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| > 1$ , then the series is divergent.
  - iii) If  $\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$ , then the test is inconclusive (and another test must be used)
- 11. Power Series: A power series is a series of the form

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + \dots + c_n x^n + \dots \text{ or}$$

$$\sum_{n=0}^{\infty} c_n (x-a)^n = c_0 + c_1 (x-a) + c_2 (x-a)^2 + \dots + c_n (x-a)^n + \dots \text{ in which the center } a$$

and the coefficients  $c_0, c_1, c_2, ..., c_n, ...$  in the polynomial are constants. The set of all numbers x for which the power series converges is called the <u>interval of convergence</u>

12. <u>Taylor Series</u>: Let f be a function with derivatives of all orders throughout some intervale containing a as an interior point. Then the Taylor series generated by f at a is

$$\sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x-a)^k = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!} (x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!} (x-a)^n + \dots$$

The remaining terms after the term containing the *n*th derivative can be expressed as a remainder to Taylor's Theorem:

$$f(x) = f(a) + \sum_{n=1}^{n} f^{(n)}(a)(x-a)^n + R_n(x) \text{ where } R_n(x) \text{ is the remainder terms}$$

Lagrange's form of the remainder: 
$$|f(x) - P_n(x)| = |R_n x| = \frac{M}{(n+1)!} |(x-a)|^{n+1}$$

where a < c < x and M is found by finding  $f^{(n+1)}$  and its max value on the interval of [a, x]

The series will converge for all values of *x* for which the remainder approaches zero as  $x \to \infty$ .

13. Frequently Used Series and their Interval of Convergence

$$\frac{1}{1-x} = 1 + x + x^{2} + \dots + x^{n} + \dots = \sum_{n=0}^{\infty} x^{n} , |x| < 1$$

$$e^{x} = 1 + x + \frac{x^{2}}{2!} + \dots + \frac{x^{n}}{n!} + \dots = \sum_{n=0}^{\infty} \frac{x^{n}}{n!}, |x| < \infty$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + (-1)^n \frac{x^{2n+1}}{(2n+1)!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!}, |x| < \infty$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^n \frac{x^{2n}}{(2n)!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)x^{2n}}{(2n)!}, \ |x| < \infty$$

### 14. Interval of Convergence (IOC) and Radius of Convergence (ROC).

- 1. Apply the Ratio Test to  $\lim_{n\to\infty} \frac{|a_{n+1}|}{|a_n|}$ . If the answer is:
  - a. 0, then the ROC is infinite so it converges for all x
  - b.  $\infty$ , then the ROC is 0, so it only converges at its center
  - c. |expression|, then the ROC is found by setting |expression| < 1 and getting it in the form |x-a| < R
  - d. To find the IOC, get x by itself so that -R + a < x < R + a. Plug each endpoint in the original  $a_n$  for x, simplify, and use a convergence test to see if the series converges. If it does, add the "equal to" part to the inequality.

